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blinkit: Maintaining Invariant Traceability through Bidirectional Transformations – A Technical Report

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Abstract—Following the “convention over configuration” paradigm, model-driven development (MDD) generates code to implement the “default” behaviour that has been specified by a template separate from the input model, reducing the effort of decisions for developers. For flexibility, users of MDD are allowed to customise the model and the generated code in parallel. A synchronisation of changed model or code is maintained by reflecting them on the other end of the code generation, as long as the traceability is unchanged. However, such invariant traceability between corresponding model and code elements can be violated either when (a) users of MDD would protect custom changes from the generated code, or when (b) developers of MDD would change the template for generating the default behaviour.

A mismatch between user and template code is inevitable as they evolve for their own purposes. In this paper, we propose a two-layered invariant traceability framework that reduces the number of mismatches through bidirectional transformations. On top of existing vertical (model→code) synchronizations between a model and the template code, a horizontal (code→code) synchronisation between user and template code is supported, aligning the changes in both directions. Our blinkit tool is evaluated using the dataset available from the CVS repositories of a MDD project: Eclipse MDT/GMF.

I. INTRODUCTION

Aiming at increasing productivity, “convention over configuration” is a software design paradigm to reduce the decisions for developers while preserving flexibility. Following this paradigm, model-driven development (MDD) of software projects (e.g., Eclipse Modeling Framework, EMF) generates code from models to implement the “default” behaviour, which was specified by a template separate from the input model. As users of MDD, programmers are allowed to customise the generated code, and the modelers are allowed to modify the models further. To support the eventual round-trip synchronisation of model and code [1], markers for traceability correspondence (e.g., @generated) are inserted at the beginning of the generated methods by MDD, indicating to the programmers that all changes to the model and the template will be reflected by the annotated method. In other words, any change made by programmers on such methods will get lost after another round of code generation. In order to protect such changes in the user code from getting lost, programmers are allowed to modify the @generated marker to @generated NOT, instructing the code generators to skip the user-specified methods.

This technique is common in MDD practice, for another example, the Acceleo Model2Text project uses “@[protected] ... @[protected]” annotations to enclose user-specified parts for arbitrary textual outputs. To illustrate its problematic use in Java development, we use EMF, the Eclipse Modeling Framework (EMF) [2] as an exemplar MDD framework. Using EMF, the template code is generated first, later refined manually into functioning user code. Once programmers change the model and regenerate the template code, it brings the necessity of the traceability to and from the user code.

Ideally, a round-trip engineering should be supported such that modifications can be correctly propagated in both directions [3]. Current state-of-the-art tools of MDD such as EMF maintain the synchronisation of changed model and code by reflecting them on either side of code generation. However, such invariant traceability links between corresponding model and code elements can be easily violated either when (a) users of MDD would protect custom changes from the generated code by changing @generated to @generated NOT or when (b) developers of MDD would change the template for generating the default behaviour for those @generated methods while all users’ change will be lost. In either case, a better solution would be to preserve the changes made by the users as well as the changes made on the model as long as they are consistent. In Section III, a detailed example will illustrate the problems such a mismatch can cause.

In this paper, we consider the mismatch problem between user and template codes that is inevitable as they evolve for their own purposes, and propose a two-layered invariant traceability framework that reduces the number of mismatches and merges the changes when possible through bidirectional transformations: The first layer of the framework synchronises the structural changes between the model and the template code at the API level vertically (denoted by model→code) using existing state-of-the-art MDD tools such as EMF; the second layer synchronises the behavioural changes between the template code and the user code inside the method bodies horizontally (denoted by code→code) if users wish to preserve both types of changes. Aligning these changes in both directions, our blinkit tool is evaluated using the dataset available from the CVS repositories of the Eclipse MDD projects EMF and GMF.
To effectively use the invariant traceability framework, users only need to insert a traceability marker annotation @generated INV, instructing the code generator to automatically (a) compare the differences between the current template and user methods; and (b) derive a bidirectional transformation for future code generation to reflect changes of the model or changes of the template back to the users methods. The tool gives warnings when there are inconsistencies between the template and the user code.

To verify our ideas, a prototype has been successfully applied it to changes recorded in the evolution of the GMF framework from its CVS repository, which shows that our new approach of round-trip engineering is promising and potentially useful in practice. Figure 1 presents an overview of the blinkkit framework when it is applied to the case study of EMF/GMF, where EMF is the synchronisation framework for vertical traceability and blinkit is the horizontal synchronisation counterpart.

The major technical contributions of the work can be summarised as follows:

- From a user’s perspective, a new type of annotations @generated INV is supported as explicit markers for automatic maintenance of invariant traceability between template (@generated) and user (@generated NOT) code;
- A novel algorithm is proposed for automatically generating a one-pass bidirectional transformation from the meaningful differences between the template code and arbitrarily modified user code such that the roundtrip relation between the structures of the model and the code can be correctly maintained.
- An empirical study is done on a CVS repository of the state-of-the-art MDD project GMF, telling the benefits of maintaining invariant traceability links, especially when the 178 changes to the @model parts have impact on the bodies of 54% of the 28,070 revisions of methods marked by @generated NOT.

Comparing to existing MDD and traceability approaches, blinkkit derives invariant transformations automatically from meaningful changes in the source code [4]. Unlike our initial work that proposes to apply bidirectional transformations directly on class diagrams and Java code [5], this work takes full advantages of the state-of-art synchronisations of many-to-many vertical traceability links between the model and the template code, such that the horizontal bidirectional transformations are applied only to the method bodies relevant to the user-modified behaviours. Since the template and the user method code are at the same level of abstraction, blinkit is allowed to derive a forward transformation from the user method to the generated method. There is no longer a need, like [5], to monitor the execution logs of user-specified ATL transformations.

The remainder of this paper is organised as follows: Section II gives some preliminary knowledge on EMF framework and introduces the bidirectional transformation mechanism implemented by the blinkit tool. Section III provides one motivation example to illustrate the synchronisation problem of invariant traceability. Section IV gives an overview of the road-trip process for horizontal and vertical invariant traceability and indicates the position of the blinkit tool in the process. Section V describes the technical details of the blinkit tool in terms of the bi-similarity properties, the generation of bidirectional transformations from meaningful changes, and the one-pass optimisation for improved efficiency of the transformations. Section VI presents the observations of the CVS evolution history of the GMF project to show the number of cases where the @generated INV markers can help. Section VII compares the related work and Section VIII concludes the paper.

II. BACKGROUND

A. EMF as a state-of-the-art MDD framework

The Eclipse Modeling Framework (EMF) [2] is a MDD framework and a code generation facility for building Eclipse tools and other applications around a structured model. From a metamodel specified in XMI or XML Schema [6], EMF generates default (i.e., template) Eclipse plugin tools that consist of Java classes for manipulating the model, along with Java adapter classes for viewing and editing a model. From a rather complex metamodel, it is impractical to generate all source code because programmers may customise the default behaviour by modifying some parts of the code in order to achieve their own goals. Using EMF, the template code is generated first, later refined manually into functioning user code. Once programmers change the model and regenerate the template code, it brings the necessity of the traceability to and from the user code.

The MDD part of the EMF consists of one code generation component (i.e., JMerge) to generate source code from a metamodel (i.e., .ecore). The template used by the code generator is specified in the JavaJET template language similar to that of JSP, which will concretise the template variables with the default values specified in the corresponding .genmodel configuration files. There is no one-to-one mapping between a class operation to a Java method in this code.
Fig. 2. Architecture of the GRoundTram system

generation: A class in the class model can be implemented in multiple classes in the model, impl, util, edit, and editor packages scattered across the generated model, edit, editor, and test plugins. In addition, there will be Package and Factory classes created and instantiated by the classes in the model. Therefore, it is not easy to maintain such many-to-many relationships using traditional traceability links techniques.

Note that EMF will be used in this study both as a subject matter (as part of the MDT case study), as well as a component of our solution. Parts of the EMF tool were generated using the EMF code generator as well. It can be seen from the existing EMF implementation that developers marked some methods as @generated NOT to preserve the changes that cannot be generated from the Ecore models alone. It is therefore common to say that code generated from EMF will be modified by users in practice.

B. Bidirectional Transformation

We use GRoundTram [7] to do bidirectional transformation for graphs. GRoundTram provides a well-behaved framework for bidirectional model transformation that guarantees the roundtrip property in bidirectional transformation. Figure 1 depicts an architecture of the GRoundTram system. A model transformation is described in UnQL+ [8], an extension of the SQL-like graph query language UnQL [9] with three graph update constructs to achieve efficiency and expressiveness, namely Replacing, Deleting, and Extending. The model transformation is then desugared to the core algebra (UnCal) which consists of a set of constructors for building graphs and a powerful structural recursion for manipulating graphs. This graph algebra can have clear bidirectional semantics and be efficiently evaluated in a bidirectional manner [10]. Graphs (models) in UnQL+ are rooted and edge-labelled ones (i.e. all information is stored as labels on edges rather than on nodes and the labels on nodes have no particular meaning), and represented in UnCAL or the standard Dot format which can be visualised and edited by the popular Graphviz tool [11].

To have a concrete idea of UnQL+, consider a simple graph $\db$ (the root is the node 1) in Figure 3. We can select the subgraph pointed by the edge labelled $b$ from the root by

$$\text{select } g \text{ where } \{b : g\} \text{ in } \db,$$

delete the subgraph (rooted at node 5) reached by the path $b.a$ by

$$\text{delete } b.a \rightarrow \_ \text{ in } \db,$$

and insert a subgraph $G$ under the node reached from the path $a.a$ by

$$\text{extend } a.a \rightarrow \_ \text{ with } G \text{ in } \db.$$

III. A Motivating Example

To illustrate the problem concretely, we use a constructed example here. Suppose a user of the EMF specifies initially a simple model that consists of one Entity class with a single name attribute. Using the code generation of EMF, she will obtain a default implementation which consists of 8 compilation units in Java (Figure 4).

Figure 5 lists parts of the generated code. The Entity Java interface has both getter and setter methods for the name attribute. They are commented by @generated annotations which indicate that the methods are part of the default implementation. Similarly, such @generated annotations are added to every generated element in the code, e.g., shown in the skeleton of EntityImpl Java class.

The annotation @generated defines a single-trip traceability contract from the model to the annotated code element. A change in the model or a change in the modeling framework
can propagate to the generated code; however, a change on these generated code will not cause a change to the reflected model and will thus be discarded upon next code generation.

Because the default implementation is not always desired, the code generation shall keep user specified changes as long as they are not inside the range of generated traceability. This can be achieved by adapting the @generated annotation into @generated NOT, a non-binding traceability that reflects programmers’ intention that it will not be changed when the implementation code is regenerated. Note that such non-binding traceability indicated by @generated NOT is still different from those without any annotation at all; Without such an annotation, EMF will generate new implementation of a method body following the templates.

However, this workaround is not ideal. Suppose a user parameterises the toString method in order to append an additional type to the returned result. To guard her method from being overwritten by future code generations, the annotation @generated NOT is used. She also applies a Rename Method refactoring, changing the getName method into getId. The modified parts are shown in Figure 6. Propagating these changes back to the model, the name attributed will be automatically renamed into id, following the naming convention that attributes start with lower case identifiers.

The regeneration of the code will result in changes in Figure 7: the setter methods and the implementations of both getter/setter methods are modified according to the default implementation of the new model. These are expected. However, two unexpected changes are not desirable. First, a compilation error results from the change in the default implementation, where the attribute name used in the user controlled code no longer exists. Secondly, the default implementation of toString method is generated with the original signature, which will of course become dead code since the user has already modified all call sites of toString to reflect the insertion of new type. Similarly, the user specified toString method can also become dead code, if it is no longer invoked by the new default implementation.

Compilation errors are relatively easy to spot by the programmer with the aid of Eclipse IDE, the dead code problems are more subtle and more difficult for developers to be aware of the consequences.

Ideally, the user is in full control: she can specify which parts of the code are in the traceability contract so that the default implementation is kept, and which parts of the code are not in the traceability contract so that her changes there will not be overwritten. For this purpose, a new annotation for invariant traceability (@generated INV) will be used in our proposed approach. As a result, Figure 8 illustrates the changes to be propagated to users’ code after our approach of bidirectional transformation is adopted.
1 //** @model */
2 public interface Entity extends EObject {
3   /** @model */
4   public String getName();
5 }
6 ...
7 //** @generated */
8 public class EntityImpl extends EObjectImpl
9   implements Entity {
10   /** @generated */
11   public String getName() {
12     return m_name;
13   }
14   //** @generated */
15   public String toString() {
16     if (isProxy()) return super.toString();
17     StringBuffer result = new StringBuffer(super.toString());
18     result.append(" (name: ");
19     result.append(name);
20     result.append(" )");
21     return result.toString();
22   }
23 } //EntityImpl

Fig. 7. Regenerated code from the model: insertions are underlined and the deletions are striking-out. compilation error is double_underlined.

IV. OVERVIEW OF blinkit

The prototype blinkit* supports our idea of maintaining the traceability of the user code and template code through bidirectional transformation. Figure 9 gives an overview of the dataflow of the components inside blinkit. The solid arrows represent three types of operations made by developers while the open- and close-ended dash arrows represent forward and backward transformations, respectively. First, developers define an original EMF model and generate template code from EMF engine (1). Developers may modify the template code into user code to meet their requirements and mark some parts of their code with annotation @generated INV (2). Developers can change the model if needed (3) and regenerate the code (4). Note that, without blinkit, step (4) may lead to the loss of developers’ modifications.

Having the above steps performed by developers, blinkit will do bidirectional transformation between user code and modified template code. In the forward transformation, we generate transformation language UnQL+ automatically by comparing the user and template code 1. The forward transformation takes user code and UnQL+ as inputs and generates intermediate code. In the backward transformation, intermediate code and modified template code are used as inputs and the output is the modified user code which not only reflects

†Actually, we represent the code by specific graphs and compare the graphs to generate UnQL+. See Section V-A.

Fig. 8. The use of invariant traceability to propagate changes in the backward direction: underlined and the deletions are striking-out.
the changes of the model but also conserves the modifications applied by developers in step 2. Notice that the intermediate code is the same as template code in our approach. We do not substitute it by template code because it separates the forward and backward transformation and makes the transformation process clearer.

First, we start Eclipse and have an initial state (Figure 9(a)). There are two buttons on the left side: one is “Create an Example”; the other is “Sync”. Second, we could click “Create an Example” button to create a new EMF project (Figure 9(b)). In the example we automatically created, there is a model named Entity. Third, we generate template code by clicking “Sync” button (Figure 9(c)). We can find there are a group of Java classes and UnCal files generated. Forth, suppose we edit the toString method in EntityImpl by changing statement result.append(" (name: ") into result.append(" (ID: "); and we also have to change the annotation @generated on toString method into @generated INV (Figure 9(d)). Then we could also change the our model from getName into getID in the interface Entity. Finally, we click “Sync” button again to regenerate code and at the same time synchronize the model and code element† (Figure 9(e)). We can find now for all the fields and methods which are annotated by @generated or are annotated by @generated INV but not edited, their names changes from “name” into “id”. But for those code user edited and marked by @generated INV, they are unchanged (e.g. the result.append(" (ID: ") in toString method of EntityImpl class is unchanged; if we do not mark it by @generated INV, it would change into template code). Therefore, this process reflects what we want to do in the motivation example.

Note that blinkit needs a large memory space to run, thus we have to allocate a large memory space when starting it. For Mac OS, we use command open blinkit.app --args vmargs -Xms256m -Xmx 1024m -XX:MaxPermSize=256m to start it; for Win32 OS, we have to config eclipse.ini in Eclipse installation directory by adding -Xms256m -Xmx1024m.

We also have a debug version of blinkit for developers. In the debug version, we divide the functionality of button “Sync” into three smaller functionalities. The steps involve in the debug version can be referred to Appendix 3.

V. IMPLEMENTATION OF blinkit

We will illustrate the implementation of blinkit by first explaining the overall process, then providing details for the critical steps for correctness and efficiency.

A. The Overall Process

We use GRoundTram system to perform bidirectional transformations and to keep the traceability of the model and code element. GRoundTram adopts input graphs which are represented in UnCal or Dot [12] format. Thus, in order to perform bidirectional transformations on Java code generated by EMF through GRoundTram, we first translate Java code into UnCal or Dot (i.e. using UnCal or Dot to represent Java source code). When translating Java code into UnCal or Dot, we adopt the EMF model as an intermediate representation of Java code since EMF model is much more navigatable than specific abstract syntax trees and can be manipulated more easily. After we get the UnCal or Dot graphs, we can generate UnQL+ [13] automatically and perform bidirectional transformations through GRoundTram.

To achieve such a round-trip process, our framework involves four engineering steps on either side of the forward/backward directions to support the code<->code horizontal synchronisation between the evolving template and user code (see Figure 10). Without loss of generality, in the following we denote the template and user codes as T and U, the modified template and user codes as T′ and U′, and the merged code as T′ ⊕ U′, respectively.

1) Given that Java codes T, T′ were generated and synchronised from the model using EMF's in-built vertical synchronisation with user's Java codes U, U′ except for those methods that are marked by @generated INV, we first parse all the @generated INV methods in T, T′, U, U′ using the JaMoPP parser on top of the EMFtext framework (see http://www.jamopp.org), their differences between the T and U′ are obtained using the API of the EMFCompare framework (see http://www.eclipse.org/emf/compare) after the meaningful differences were preprocessed using mct (see http://sead1.open.ac.uk/mct [4]);

2) The EMF models of T, T′, U, U′ are translated into our specific UnCal graphs using the reflexion API of the Ecore, and as a by-product, an UnQL+ transformation is generated from the meaningful differences between T and U′ using the algorithm in Figure 11;
3) The UnCal graphs of $T, T', U, U'$ are transformed into Dot graphs by the GRound_Tram system that preserves the paths from the graph root to any node on the UnCal graphs in the equivalent Dot graphs;

4) Using the generated UnQL+ transformation and using the Dot graphs of the $U'$ as inputs, the GRoundTram system also performs a forward transformation to output a group of Dot graphs that represent $T$, which is guaranteed by the one-pass optimisation described in Section V-C;

5) On the way backwards, using the same UnQL+ transformation on the Dot graphs of the modified template code $T'$, and the internal graph traceability between $T$ and $U'$ kept by the forward transformations in GRoundTram system, the GRoundTram system performs a backward transformation to output the Dot graphs that represent the merged user code, denoted by $T' \oplus U'$;

6) Path-equivalent UnCal graphs corresponding to $T' \oplus U'$; are re-generated from the resulting Dot graphs;

7) Equivalent EMF model of those UnCal graphs for $T' \oplus U'$ is obtained using an xtext parser (see http://www.eclipse.org/Xtext) of UnCal to process the its abstract syntax using the EMF API;

8) Finally, the merged Java code $T' \oplus U'$ is obtained from the EMF model using the pretty-print function of the JaMoPP framework.

![Diagram](image)

Fig. 10. The multi-tier architecture of the blinkit framework.

B. Generating correct UnQL+ transformations

To enable the use of UnQL+ on model-driven software development, we need to losslessly translate the artifacts between the code, the UnCal graphs and node-traced graphs such as Graphviz Dot. This can be done in a multi-tier fashion [14], and one critical step is to guarantee the correctness of the horizontal (code\textasciitilde code) synchronisation, that is to generate a correct UnQL+ bidirectional transformation from the meaningful differences of the original template code and the modified user code.

**Code Generation from Model.** From model to code, we rely on the existing EMF framework, which provides a well-established way to synchronise the model and default code template (i.e. the code marked by @generated). Reusing this tool, we do not need to develop any model-to-code vertical synchronisation tool ourselves. But we distinguish the template code which users do not want to synchronise by themselves and those code they want. We also need to automate the manual code synchronisation process such that it is possible to make the whole tool chain automated. Thus we intercept the automated code generation process in EMF as follows: When generating code from model, for those code marked by @generated or @generated NOT we use default code template generated by EMF; and for those code marked with @generated INV, we use the code of synchronised version whose traceability are maintained by GRoundTram. Then we merge these two kinds of code together and expose the merged code to users.

**Transformation between Code, EMF model, UnCal, and Dot.** We choose EMF model as an intermediate representation of the Java code because (1) EMF model is much more navigatable than specific abstract syntax trees and (2) it also make the translation from the abstract syntax to the uncal generic: any programming language can be supported in future. EMF reflection mechanisms are used to facilitate the translations. From EMF to UnCal, an algorithm is designed to traverse the model and print out the node types, references and attributes according to the programming language model. In blinkit, we leverage xtext [7] and EMFText [7] to do such translations. For UnCal to EMF model, an algorithm is designed to reflect the generic language model in UnCal to a specific EMF language model such as Java. It is found that xtext is a suitable choice because the generic UnCal language is not too complex to parse. Though the input of GRoundTram system can be in UnCal format or in Dot format, the outputs are always in Dot format. To separate each tier, we use Dot graphs as GRoundTram inputs universally, so we have to translate UnCal to Dot and vice versa. We design and implement an algorithm to translate $\oplus$ into the specific UnCal format, in order to perform backward transformation. Since GRoundTram could translate UnCal to Dot, we do not need to design a new algorithm to create this translation while performing forward transformation. Another problem is that since GRoundTram needs node-traced graphs while performing backward transformation, we keep the constants of the node number in Dot graphs resulted from a forward transformation otherwise the GRoundTram could not perform backward transformation (i.e. we have to maintain the traceability of the Dot when do transformation). While performing backward transformation, we generate the Dot from the UnCal and reserve the physical relations (i.e. the node number in Dot) in the Dot graph generated from forward transformation. Our approach to reserve such physical relations is based on comparing Dot graphs, which is similar to the algorithm used for generating UnQL+ (Figure 11).

**Generating UnQL+ and Do Bidirectional Transformation using GRoundTram.**

After having the Dot graphs, we can use them as inputs and perform bidirectional transformations through GRoundTram. Note that GRoundTram needs to use bidirectional transformations specified in the UnQL+ graph transformation language which extends the UnQL [9] with three simple graph editing
constructs to achieve efficiency and expressiveness [8], namely Replacing, Deleting, and Extending. Deleting will delete a subgraph under a specified edge while extending will insert a subgraph under a specified node, and replacing will replace a part of the given graph with a new subgraph. As we said in Section IV, the UnQL+ is used in forward transformation to transform user code into intermediate code which is the same as template code. We implemented an algorithm shown in Figure 11 to generate the UnQ+ transformation automatically in order to mitigate developers’ burden. After representing the Java code that we want to synchronise by Dot graphs, we can obtain the differences between the Dot graphs and such differences can be used to generate UnQL+ automatically.

The UnQL+ generated by our approach only contains Deleting and Extending operations. The Replacing operations can be replaced by a Deleting and an Extending operation. The Replacing operations can also be replaced by two Deleting operations which will delete the corresponding subgraphs from the user’s graph and template graph respectively. The correctness of our UnQL+ generated algorithm (i.e. if there are two outgoing edges of a node with the same label, this algorithm may not generate desired UnQL+).

An example is shown to illustrate this algorithm (Figure 12). Suppose we want to transform a graph shown as Figure 12(a) into Figure 12(d), then we have to delete the edge e, g and subgraph subgraph 2, and insert the edge h and subgraph 4. The algorithm first generate Deleting operations which could transform Figure 12(a) into Figure 12(b). Note that the Deleting operations contain the deletion of subgraph 3 and edge f though they should not be deleted. This is because when the algorithm deletes the edge g, it will also delete its pointed subgraphs (subgraph 3) and the edges connect to those subgraphs (edge f). Then when generating extending operation, the algorithm not only inserts the edge h and subgraph 4, but also inserts the edge f and subgraph 3 again. This extra deletion and insertion may reduce the transformation efficiency and more efficient algorithms should be explored in the future work. Comparison algorithms for trees and graphs based on dynamic programming [15] may be adopted.

C. Derivation of a One-Pass Transformation

The automatically generated UnQL+ transformations, like SQL queries, are not optimal unless some optimisation can be made. One bottleneck of its performance is that the pairs of difference elements as basic operations Replacing, Deleting or Extending on the source code are typically multiple, while the

![Fig. 11. Procedure of generating UnQL+.](image-url)
original form of UnQL+ would sequentially compose them. Ideally, these operations should be composed as one single graph transformation such that GRound_Tram could attain results in one-pass of the structure. In theory, the composition of general UnQL+ transformations have to be sequential. However, the transformations we obtained from the diff results have nice properties that make it possible to compose the basic operations without any side-effects. The rationale is given below.

Let $e_1, e_2, \ldots, e_n$ be a sequence of the editing operations obtained above, where any two editing operations, $e_i$ and $e_j$, are independent in the sense that neither insertion nor deletion is done on an inserted/deleted part again. This can be formalised as that for any $i$ and $j$, $e_i \circ e_j = e_j \circ e_i$ holds.

We would like to show that any editing sequence can be automatically transformed to a one-pass traversal of graphs. Our algorithm consists of two steps: We first map the editing sequence to a set of graph transformation where each graph transformation corresponding to an editing operation, and then try to fuse the composition into a single one-pass graph transformation in terms of a structural recursion in UnCal.

1) Mapping from Editing Sequence to Composition of Graph Transformations: First, as discussed before, each editing operation corresponds to a simple graph transformation in UnQL+. To be precise, let $p$ denotes the path from the root to the node $n$ (i.e., a sequence of edge labels from the root to the node $n$) of in the graph $db$. Then, the editing operation $e(db)$ for deleting a subgraph $\{ l : db \}$ rooted at the node $n$ can be translated to $E(db)$:

$$\text{delete } p \rightarrow \{ l : db \} \text{ in } db$$

and the edition operation $e'(db)$ for inserting a subgraph $G$ to the node $n$ to $E'(db)$:

$$\text{extend } p \rightarrow G \text{ with } G \text{ in } db.$$  

Now a sequence of editing operations $e_1, e_2, \ldots, e_n$ corresponds to composition of graph transformations of $E_1(db), E_2(db), \ldots, E_n(db)$, that is,

$$E_1(E_2(\ldots(E_n(db)))).$$

2) Fusion of Composition of Graph Transformations: GRound_Tram provides a powerful fusion mechanism that can automatically fuse a composition of graph transformations into one so that unnecessary inter mediate graph passed between the graph transformation can be eliminated. We could apply this general fusion mechanism, but we can do better based on the fact that each graph transformation is independent from each other. Thus we develop a specialised but more efficient fusion algorithm.

Our idea is to construct an action tree from the editing sequence and then map the action tree to a one-pass transformation. For an action tree, leaves are marked with two action markers $D(l)$ and $I(G)$, denoting respectively deletion of a graph pointed by the edge $l$ when possible and insertion of a graph $G$. Figure 13 gives an example action tree, which describes the intention of that, given a graph, for the node reached by the path of $a.b$ do deletion, for the node reached by the path $b.a$ do deletion, and for the node reached by the path $b.c$ do insertion. In fact, an action tree is nothing but a tree automaton, and it is known that a tree automaton can be mapped to a structural recursion in UnCal that traverses graphs only once [9].

Let us show that a sequence of editing operations can be represented by an action tree. First, it is clear that a single editing operation can be represented by a simple action tree (which is actually a tree where each node has just a single child). Now given two action trees $t_1$ and $t_2$, we can combine them to $\text{merge}(t_1, t_2)$, satisfying that (1) any action in $t_1$ or $t_2$ appears in $\text{merge}(t_1, t_2)$ and any action in $\text{merge}(t_1, t_2)$ appears in in $t_1$ or $t_2$ and (2) there is no node that has two outgoing edges with the same labels. The algorithm $\text{merge}(t_1, t_2)$ is define as follows:

$$\text{merge}((), t_2) = t_2$$
$$\text{merge}(t_1, ()) = t_1$$
$$\text{merge}(t_1 \cup t_1, t_2) = \text{merge}(t_1, \text{merge}(t_1, t_2))$$
$$\text{merge}(l : t_1, \{ l : t_1 \} \cup t_2) = \{ l : \text{merge}(t_1, t_2) \} \cup t_2$$
$$\text{merge}(l : t_1, t_2) = \{ l : t_1 \} \cup t_2$$

With this merge operation, we can merge all editing operations into an action tree.

VI. Evaluation

In order to evaluate the benefits of the framework, we assess two research questions. First, does blinkit work correctly on the examples without human intervention? Second, given that the illustrative example is constructed, is there realistic cases in an open-source MDD software development project where invariant traceability links can be synchronised using blinkit? The first question needs to be answered first since only a working blinkit prototype can bring benefits to the users if it is beneficial. The second also needs to be answered since if there is no evidence blinkit is needed in the practice, one might question the usefulness in reality. To answer these questions, we conducted two sets of experiments.

Correctness. In the first experiment we create a model in EMF framework as the one illustrated earlier and generate the default Java source code initially. Table ?? shows the number of elements at various abstraction levels in the generated code. There is only 1 class (i.e., Entity) and 1 attribute (i.e., name) respectively in the EMF metamodel, the code generated by EMF has 2 classes (i.e., Entity, EntityPackage) and 1 attribute (i.e., name) annotated by @model. In terms of the number of @generated attributes, there are respectively 8 classes, 48 attributes and 10 methods generated in 3 packages.
Currently, blinkit only supports synchronisation between method bodies which user likely to change for different behaviours according to our experience.

For evaluating the correctness of blinkit, we manually modified those 9 methods annotated by @generated into @generated INV. The blinkit tool generated an ‘identity’ UnQL+ transformation for each of the invariant traceability @generated INV. Then we manually modified individual @generated INV methods in three ways: By adding, removing and replacing 1 or 2 statements to simulate a possible change on the user code. In parallel to that, we applied the Rename Class and the Rename Method refactorings to the 3 elements in the model that were annotated by the @model markers to impact on the template code.

The simulated changes to the newly generated template code may intersect with the changes introduced by user, e.g., by renaming “name” to “ID”, in those cases the changes should be merged by blinkit. For correctness, we checked the merged results manually to see whether they preserve both changes in the model and in the user code. On the other hand, if the changes of the @model do not affect the changes to the @generated INV elements by the user, then all changes introduced by the user were preserved.

Intersection of the changes in @generated NOT, @generated and @model. To answer the second question, we first extracted from the CVS repository all revisions of Java code from the GMF project according to http://archive.eclipse.org, which covers about 6 years period between Aug 14 2005 and Aug 31, 2011. According to this repository, in total there have been 28,070 revisions including all the ones before the deleted files were placed in the Attic subfolders. In order to understand how many times the model parts have changed, we rely on the EMF convention that all modeling elements in the generated template code have been annotated with the @model markers. Therefore, we extracted the interface APIs that were marked by @model using the normalisation and clone detection technique reported in our earlier work [4]. In this way, all meaningful differences for the model can be found among the 1185 pairs of possible revisions (we only compare those revisions on the same files). There are 178 pairs of meaningful changes, ranging from 2005/08/14 till 2011/02/28. There is no longer changes after that. Figure 14 shows the distribution of 178 @model changes over this period of time.

Next, we used a different normalisation on the same dataset, this time filtering only those methods that have been annotated by @generated NOT markers amongst 1,314 Java classes. For these Java methods, we moved their implement-

<table>
<thead>
<tr>
<th>Abstraction</th>
<th>@generated</th>
<th>@model</th>
</tr>
</thead>
<tbody>
<tr>
<td>packages</td>
<td>3</td>
<td>0</td>
</tr>
<tr>
<td>classes</td>
<td>9</td>
<td>2</td>
</tr>
<tr>
<td>declarations</td>
<td>48</td>
<td>1</td>
</tr>
<tr>
<td>method bodies</td>
<td>9</td>
<td>0</td>
</tr>
</tbody>
</table>

Table I

Statistics on the Entity Example

Throughout the dataset, it is found that 15,223 revisions amongst the total of 28,070 revisions (i.e., 54%) will be influenced by the changes of the @model elements, and on average 146,415/15,223=9.61 of the modeling elements are referenced by the method implementation of the @generated NOT parts of these Java revision files.

We briefly summarise the threats to validity and some limitations in this study:

Construct validity: Instead of synchronising for the whole classes or packages, we focus on synchronising changes to the method bodies. The reason for this choice is practical as most of the time the user would customise the behaviour of the default class, rather than rewriting them completely. Also to note that a modification to method bodies is often required because the template code would otherwise raise UnsupportedOperationException.

External validity: blinkit is built on top of existing open-source MDD toolsets EMF, EMFtext, JaMoPP and a standalone transformation systems TXL. It also integrates two research prototypes groundzeam [16] and mct [4] which are freely available to download. The subject case study is also an open-source one whose CVS repository is publicly available.

Internal validity: Although studying committed changes on the model in the GMF repository may be conservative, it is the only publicly available source code that we can rely on. It can be argued that editing changes that were not committed may have more opportunity of synchronisation, however we have to make conservative estimates on the benefits without empirically monitoring developers over their shoulders.

VII. RELATED WORK

We compare blinkit to the related work in the areas of traceability, model-code co-evolution, and bidirectional transformations.

Precise traceability. Automated software document-code traceability recovery has been studied by researchers from many angles since requirements traceability was proposed [3]: The review of the best practices in this field [17] suggests that automated techniques such as vector spaces [18], [19], LSI [20] are useful when part of the dataset relies on ambiguous documentation such as requirements, manuals and bug reports. It is expensive to obtain expert judgements for large applications [21] and to obtain high-quality inputs [22].
Incremental techniques have been proposed to analyse evolving traceability links [20] for better efficiency, however, precision cannot be greatly improved. Auxilliary information from programs such as callgraphs or traces [22] could help improve the precision to some extent, but it is still largely expensive to gain better results through feedback [23]. On the other hand, the abstraction gap between models and code is much narrower that that between requirements document and code, thus precise tracing has been considered through maintaining semi-automated refactorings [24]. However, such refactorings are also expensive to construct, thus affordable only for medium-sized security software applications. In this work, we address the problem for general software projects that scales while the MDD has been applied.

**Invariant traceability for model/code co-evolution.** When projects evolve, MDD methods face additional challenges: not only do artifacts such as models or code change over time, their changes also need to be propagated in order to maintain consistency even when artefacts are at different levels of abstraction. *Co-evolution* needs to be studied between models and code, between behavioural and structural models, or even between code and programming languages [25]. Modifications to a model must be reflected on the corresponding code in order to keep the model and the code *synchronised*. Code generators exist to automatically generate code from UML models [26]–[28]. However, in practice the code is often updated manually after it has been generated, and it is therefore necessary to reflect those changes back to the corresponding model. Round-trip engineering (RTE) is one-way to synchronise UML diagrams and code [29]. However, combining code generation and reverse engineering approaches is still not sufficient: Changing independently, models and code need to be *merged* first; Secondly, since models are generally at a higher level of abstraction than code, not all changes made to the code can be reflected back to models. There may be changes on a level of abstraction that is too detailed for the model. Therefore, for every model, there exist many different versions of the code that implement the model correctly. Giese and Wagner [30] use triple graph grammars for RTE, but their approach is limited to elements that have a correspondance in the model. Other approaches, like Van Paesschen et al.’s [31], assume that both artifacts can be represented in a common representation. Fujaba [32] is yet another RTE approach that can generate Java code from UML class diagrams, and regenerated class diagrams from modified Java code, as long as developers follow Fujaba’s naming conventions and implementation concepts. State-of-the-art RTE tools such as EMF/GMF make use of annotations to separate the portions of generated and user modified code, yet it is largely manual to maintain the correspondence of @generated NOT elements. In order to allow one to preserve changes made to the code when the model is updated and the code subsequently regenerated, tools such as the EMF and GMF frameworks allow developers to annotate portions of the code to make sure that they will not be overwritten by the code generator in the future. While this solution allows one to protect custom code from being overwritten, over time, the model and the code will become increasingly inconsistent, as some changes performed on the model will not be reflected in the code. The co-evolution of GMF project has been studied [33] for synchronising the four different EMF metamodels (model ↔ model) used by the project. Although we also uses the same case study to evaluate the benefits, our focus is on automating the code ↔ code synchronisations for method bodies.

**Bidirectional transformation** [34], [35] has been recently widely studied by researchers from different communities of programming language, software engineering, and database. It has many potential applications in software development, including model synchronization [5], [36], round-trip engineering [37], software evolution [38], and multiple-view software development [39]. Our work shows that we can move from “potential” to “practical”; we achieve scalability by proposing a two-layer bidirectional transformation framework, hiding difficulties in writing bidirectional transformation by automatic deriving it from a sequence of editing operations, and widening its application scope by treating general graphs.

**VIII. Conclusions and future work**

In this paper, we presented a model-driven development method, supported by the blinkit prototype, to maintain the invariant traceability between model and code through bidirectional transformations. Using this method, if the code is annotated by @generated INV, a bidirectional transformation will be generated which correctly propagates changes in both directions. We tested our framework by the example shown in Section III and observed empirically how often blinkit can be used to maintain the invariant traceability.
based on the dataset of the CVS repository of GMF, a widely-used model-driven development project. It is also observed that applying the method to the project can deliver more benefits since its metamodels changes more frequently.

In the case study, we also found that more changes were derived from the evolving model than from the evolving template. Current work considers a basic form of invariant traceability where all meaningful changes are synchronized, regardless whether they were derived from the template or from the model. In future work, we will extend the syntax and semantics of \texttt{INV} to further differentiate the changes from model from those from the templates.

REFERENCES


